1	Mate detection in a territorial butterfly – the effect of background and luminance contrast			
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## 17 Abstract

18 Many animals search for potential mates or prev using a perch-and-sally strategy. The success of 19 such a strategy will depend on factors that affect the observer's ability to detect a passing 20 resource item. Intrinsic factors (e.g. eye structure and physiology) have received much recent 21 attention but less is known about effects on object detection in nature and extrinsic factors such 22 as size, coloration and speed of a passing object and the background against which the object is 23 viewed. Here, we examine how background affects the detection of butterfly models by perched 24 males of the butterfly Asterocampa leilia in the field. We test the hypothesis that male choice of 25 perch site in nature will influence the contrast between the object and background against which 26 it is viewed, and that this will influence success in detecting the object. We also test the effect of 27 contrast by manipulating the brightness of the object and presenting butterfly models of different 28 reflectance (ranging from black to white). We found an effect of model luminance, with dark 29 models being most likely to elicit a response regardless of background. Further, there was an 30 effect of background type with models viewed against blue sky eliciting the highest response. 31 Perceived luminance contrast correlates to behavior; highly contrasting objects are more 32 frequently detected. This study expands our understanding of visual system performance and has 33 implications for our understanding of the behavior and evolutionary ecology of perching species. 34

# 35 Key words: Lepidoptera; mate locating behavior; perching; sexual selection; perching;

36 territoriality; vision

#### 37 Introduction

38 Many animals visually search for resources such as potential mates or prevusing a perch-and-39 sally strategy. This strategy involves individuals waiting at some vantage point on the lookout for 40 mates or prey passing by and then sallying out to intercept, investigate and pursue any objects of 41 potential interest. Perch-and-sally tactics are a widespread and conspicuous component of animal 42 behavior in both invertebrates and vertebrates (Atkins 1980; Thornhill & Alcock 1983; Remsen 43 Jr & Robinson 1990). This strategy contrasts with patrolling (actively searching) as a way to 44 locate mates or prey and the perch-patrol dichotomy in mate locating behavior and hunting 45 strategies is well established in the literature on insect behavioral ecology (Scott 1974; Ehrlich 46 1984; Rutowski 1991; Corbet 1999; Wiklund 2003; Corbet & May 2008).

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48 Even though perching as a mate locating tactic or hunting strategy is widespread, little research 49 has been done to understand the factors that contribute to success in detecting, intercepting and 50 pursuing moving objects of interest. This is peculiar because the behavior is strikingly similar 51 among all perching species and success in this activity should have a huge effect on the 52 performer's fitness. A more comprehensive understanding of the proximate factors that influence 53 male's success in mate searching or hunting, especially factors influencing visual mate detection, 54 will give us more insight in the potential adaptive features of mate-locating behavior and mating 55 system structure in insects.

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57 Both *intrinsic* and *extrinsic* factors will influence a percher's visual detection of passing objects.

58 Over the last few decades our understanding of intrinsic factors, such as visual system

59 performance, has increased due to studies of eye structure, optics and electrophysiology (Land &

60 Nilsson 2012). However, less attention has been given to the role of extrinsic factors such as

61 object size, coloration, pattern and shape, the speed of the object, the properties of the 62 background against which the object is viewed, perch location, and the positioning of the 63 observer in relation to the object and its path. These factors will cause variation in ambient light 64 levels, contrast between the object and the background and blurring effects, which are all known 65 to be key elements in visual acuity and target detection (Land 1997; Rutowski 2003). Intrinsic 66 factors studied in controlled laboratory environments have been the focus of attention in the last 67 few decades. However, extrinsic factors are ideally examined under field conditions, where 68 experiments are logistically more difficult and more difficult to control but yield results more 69 directly relatable to what the animals are doing in nature. In species that use a perching strategy 70 to find mates or prey, we expect strong selection on behavior to adapt to environmental, extrinsic 71 factors, in order to optimize success in mate searching or hunting.

72

One of the relatively few species that has been studied in the field to understand visual aspects of perching behavior is the Empress Leilia butterfly, *Asterocampa leilia*. Males of this nymphalid species perch in the morning from about 8 to 11 AM on or adjacent to the larval food plant, desert hackberry (*Celtis pallida*), and wait for females to pass by (Austin 1977; Rutowski & Gilchrist 1988). From his perch, the male flies out to investigate passing objects. Conspecific females are pursued and courted, whereas conspecific males are chased away from the perching site (Rutowski & Gilchrist 1988).

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During the course of a morning's activity, males of *A. leilia* can adopt two different perching positions: (1) on the ground, next to a hackberry tree, or (2) on the hackberry tree at a height of about 0.85 meters, the same height at which *A. leilia* females fly through the habitat (Rutowski 2000). Males start the morning perching on ground but shift to perching off ground, on hackberry 85 trees as temperatures rise (Rutowski *et al.* 1991). The change of male's perch preference is driven 86 by thermoregulatory issues; ground temperatures can exceed the tolerable thermal maximum for 87 A. leilia, while temperatures are lower at 0.85 m, the typical perch height of A. leilia (Rutowski et 88 al. 1994). Perch location influences the male's ability to detect passing objects. In a field study, 89 Rutowski et al. (2001) presented butterfly models to perched males and found that males on 90 ground were more likely to initiate pursuit of a passing model than those off ground. The body 91 posture of males perched on the ground (body pitch upward about 30 degrees and facing away 92 from the sun) is different from that of males perched on the ground (body pitch slightly down, 93 facing out of bush; Rutowski 2000). This difference in body posture with perch location means 94 the equatorial acute zone of their eyes (Rutowski and Warrant 2002) is directed slightly 95 differently relative to the likely flight path of conspecifics. However, this difference suggests that 96 males on the ground should be less likely to detect conspecifics passing through the territory, 97 contrary to what was observed.

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99 Alternatively Rutowski et al. (2001) argued that differences in the rate of response was most 100 likely because males perching above ground are likely to view passing conspecifics against a 101 relative dark background of nearby vegetation, while males perching on ground are likely to have 102 the relatively bright and uniform blue sky as the background. Rutowski et al. (2001) crudely 103 tested this hypothesis by increasing the flight height of the models, to change the potential 104 viewing background for perched males. And indeed, this change increased the proportion of 105 males that responded to the models (Rutowski et al. 2001). However, the authors did not explore 106 this issue further.

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108 Other studies have also shown that background affects the detection of passing conspecifics or 109 prev (Labhart & Nilsson 1995; Switzer & Eason 2000) but few studies have further investigated 110 what properties of object and background are important. Animal sense motion of a passing target 111 as temporally correlated changes in stimulation in sets of photoreceptors (Cronin et al. 2014). 112 Hence, the luminance of a target and its contrast with the luminance from a background will 113 affect the magnitude of such change in stimulation and thereby significantly affect visual 114 detectability, where a high contrast increases the change in signal and thereby detectability 115 (Buser & Imbert 1992). For an insect, this means that when luminance contrast between an object 116 and its background is high, the viewer will be able to see that object from further away, and at a 117 given distance, detect smaller objects (Mazokhin-Porshnyakov 1969; e.g. Lehrer & Bischof 118 1995). Here we experimentally explore the nature and implications of object-background contrast 119 in nature, with Asterocampa leilia as the subject. We investigate how background contributes to 120 variation in luminance contrast between a passing object and the background against which it is 121 viewed and how this will influence visual mate detection in nature. We further test the hypothesis 122 that visual mate detection is influenced by contrast by manipulating the brightness and color of 123 the object, and consequently also manipulating contrast. We presented butterfly models of 124 different reflectances (ranging from black to white) to perched males. We further, and more 125 quantitatively than previously, tested the prediction that the type of background a male chooses by selecting a perch site in nature will influence the contrast of the object and that the choice of 126 127 perch site thereby also will influence his success in detecting the object. We predict that a perch 128 site that create a high contrast between the object and the background will increase detectability 129 and perch sites with a low contrast between the object and the background will decrease 130 detectability.

131

#### 132 Material and methods

133 Study site

134 The experiments were conducted in May-June and September-October 2013 in the upper Sonoran

135 Desert in the Mazatzal Mountains of central Arizona, USA. The site, known as Round Valley (N

136 33.79784, W 111.4877), is in the floodplain of Sycamore Creek and has been used in previous

137 studies of Asterocampa leilia (Rutowski & Gilchrist 1988; Rutowski et al. 1991; Rutowski 2000;

138 Rutowski et al. 2001). The larval foodplant of A. leilia, the desert hackberry tree (Celtis pallida),

139 is abundant in this area.

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141 Butterfly model presentation device and general experimental procedure

142 Butterfly models were presented to perched males with an apparatus that has been used in 143 previous studies of mate detection in territorial butterflies (Rutowski et al. 2001; Bergman & 144 Wiklund 2009) and consisted of two metal poles, positioned eight meters apart, and each with an 145 attached pulley. The pulley on one of the poles was turned by a small electrical motor controlled 146 by a portable remote control. A loop of thin (0.65mm in diameter) nylon line was strung between 147 the pulleys and a model attached with an 8 cm line to the loop. The attached butterfly model was 148 presented to a male at a height of 0.85 m above ground. When the motor was activated, the model 149 quickly accelerated to a speed of about 4.5 m/s. For each presentation we measured the time it 150 took for the model to get from one pole to the other, i.e. to travel eight meters. We calculated the 151 speed of the model and only recorded the male's response if the speed of the model was between 152 4 and 5 m/s, the typical flight speed for this species. All models were made of 2 mm thick 153 cardboard. The models were constructed to match the size (45 mm wingspread) and shape of an 154 A. *leilia* with wings spread.

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156 We used four different types of butterfly models hereafter referred to as *black*, *gray*, *white* and 157 tan, respectively. The black and gray models were painted with an acrylic paint (Model Master 158 Acryl, ©*The Testor Corp.*), the white model consisted of white filter paper glued to the cardboard 159 model and the tan model consisted only of unpainted cardboard. The four butterfly models varied 160 in their reflectance spectra (figure 1) (for description of the measuring methods see *Reflectance* 161 section below): the black, gray and white butterfly models had a flat reflectance curve where the 162 black reflected least and white reflected most light between 300 and 700 nm. The average 163 reflectance spectrum of the tan butterfly model (26.6 +/- 2.7 %) was similar to the gray butterfly 164 model (27.6 + 1.3%) but had a shift towards longer wavelengths and thereby the coloration also 165 matched the overall ventral wing surface reflectance of A. leilia females (Figure S1). Further, tan 166 model average reflectance  $(26.6 \pm 2.7\%)$  was not significantly different from female ventral 167 hindwing average reflectance (21.0 +/- 2.33%, t-test:  $t_4 = 1.88$ , P = 0.13).

168

169 Each model presentation proceeded as follows. We located a male in the field, perched either on 170 the ground or on a hackberry tree, and set up the presentation apparatus near him. The flight path 171 of the model was set up so that it was perpendicular to a line between the perching male and the 172 midpoint of the model flight path. The distance between the midpoint of the flight path and the 173 perching male was between 1 and 2 meters for all presentations, which is a range of distances 174 where males of A. *leilia* respond most frequently to passing objects of the size and shape 175 presented (Rutowski et al. 2001). Once the apparatus was activated and the model moved from 176 one pole to the other we recorded the following information: (1) whether the male responded to 177 the passing model by flying up and pursuing the model, (2) the direction that the male faced 178 relative to north just before the model was presented, (3) the compass bearing of the flight path,

(4) the compass bearing of a line from the perching male to the nearest point of the flight pathand (5) the perch height of the male.

181

To characterize the background against which the butterfly model was viewed by the male in a presentation, we took panoramic photos with a Casio EX-ZR100 camera of the model flight path from the vantage point of the male's perch (Figure 2). This was done for all presentations during the experiment.

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187 Although the apparatus for presenting butterfly models was relatively mobile, the number of 188 potential males available on any given day was limited in time and space (cf. Rutowski et al. 189 1996; 2001). To maximize data yield per unit effort, after setting up the apparatus at a perching 190 site we presented, in randomized order, as many of the four types of butterfly models as we 191 could. However, we never presented the same model type to a specific male more than once. We 192 were able to present all four model types to 78% of the males and conducted on average 3.51 193 presentations per individual male. In total, we presented models for 51 different males and we did 194 179 presentations.

195

Occasionally, due to high flight activity, resident males engaged in territorial contests with
intruder males between different model presentations; these occurrences led to uncertainties of
whether the same male was present for all model presentations at a given site. However, in
territorial interactions the original resident most often wins the fight and returns to the perch site
(Rutowski & Gilchrist 1988; Kemp & Wiklund 2001) making a change in resident unlikely.
Moreover, even though males of *A. leilia* rarely occupy a perch site for more than one day
(Rutowski & Gilchrist 1988), we never presented models for males on the same perch site on

subsequent days and we alternated experimental areas within Round Valley to avoid running the same male twice. However, sometimes the male left or changed perch site after taking off. Hence, some of the males did not experience all four models and the sample sizes might vary between groups. This also means that across the four model types the observed responses were not completely independent. However, within any model type all responses are to our best knowledge independent.

209

## 210 Analyses and statistical methods

211 To estimate the main background for each presentation we used the images taken after each 212 presentation. In the images we overlaid the "flight" path of the model. Since earlier studies on A. 213 *leilia* have shown that the male's ability to detect passing objects is strongly affected by distance 214 and that perched males cannot detect a natural sized gray butterfly model at a distance larger than 215 3 meters (Rutowski et al. 2001), we excluded parts of the flight path that were further away than 216 3 meters from the perched male. In the images we identified three different background 217 categories against which the "flight" path was viewed: sky, vegetation and sand. With ImageJ 218 (http://imagej.nih.gov/ij/) we measured (in number of pixels) the proportion of the "flight" path 219 seen against sky, vegetation and sand respectively and the category with highest proportion was 220 considered the main background for that presentation (figure 2).

221

To analyze the effect of butterfly model type and background we used Generalized Estimating
Equations (GEE) with a binary logistic model. We used the response by the male (take-off or no
take-off) as a binary dependent variable and butterfly model type with background as predictors.
Since we have several presentations for the same male, male identity was used as a subject
variable and model type was consequently treated as a within-subject variable. As the interaction

between butterfly model type and background was non-significant it was excluded from the model when testing for the main effects of model type and background. The GEE model was run in SPSS 22. For testing the differences in response between the four model types we performed pairwise McNemar's test between each combination of model type. Four model types resulted in six pairwise tests and the  $\alpha$ -value was adjusted with a sequential Bonferroni-correction.

232

## 233 *Reflectance*

234 We collected leaves from hackberry and mesquite trees (Prosopis velutina) along with sand and 235 rocks from the field sites in Round Valley and transported them back to the lab. Vegetation 236 reflectance measurements were taken immediately to ensure that the vegetation retained its 237 natural reflectance. We measured reflectance of 20 hackberry leafs from 4 trees, 10 mesquite 238 leafs from two plants, 10 dishes of sand and each model used in the behavioral trials. For each 239 plant, we measured reflectance three times on the upper and lower surfaces of leaves. To 240 characterize the color of each model we measured reflectance at five points on the model and 241 averaged the spectra. We measured the ventral hind wing reflectance of three A. leilia females to 242 confirm that the tan model was similar in coloration to female A. leilia individuals. The ventral 243 surface of A. leilia is not homogenous, however butterflies that employ a perch and sally mate 244 location strategy are highly unlikely to have sufficient visual acuity to resolve specific internal 245 pattern elements of potential mates, given they are a small, moving target relative to their field of 246 view. With this in mind, we measured across the hind wing with a sampling area of 1 cm. To 247 collect all reflectance spectra we used a bifurcated reflectance probe (Ocean Optics) with the 248 collecting fiber connected to a spectroradiometer (USB2000, Ocean Optics, Dunedin, FL, USA) 249 and the illuminating fiber connected to a Pulsed Xenon light source (Ocean Optics). All 250 reflectance measurements were collected in a dark room with the probe positioned perpendicular

to the target surface and were measured relative to a spectralon diffuse reflectance white standard
(Labsphere, Inc., North Sutton, NH, USA). The output of the spectroradiometer was collected
with SpectraSuite software (Ocean Optics) and then raw spectral data from 300 to 700nm were
binned into one nanometer bins with CLR (Montgomerie 2008). Reflectance spectra were first
averaged for each plant and then all plants were averaged resulting in one average vegetation
reflectance. Similarly, all sand reflectance spectra were averaged for an overall sand reflectance,
and each butterfly model's reflectance spectra were averaged.

258

#### 259 Irradiance

260 Light environment (ambient irradiance) measurements were collected on 7 November 2013 from 261 five perching locations where butterfly models were presented in Round Valley. Irradiance 262 measurements were used with reflectance to estimate the radiance from the models, and the 263 radiance from background as viewed by male A. leilia in behavioral trials. The measurements 264 were made when the sky was clear from 10:00am to 12:30pm. Ambient irradiance was measured 265 separately for the butterfly models and background (i.e. sand, vegetation and blue sky). We used 266 a cosine-corrected irradiance probe (Ocean Optics, Dunedin, FL, USA) connected to a 267 spectroradiometer (USB 2000, Ocean Optics) connected to a laptop running SpectraSuite 268 software (Ocean Optics). The radiance of the butterfly models is determined by the ambient 269 irradiance from the hemisphere in the direction of the perched male, multiplied by the diffuse 270 reflectance of the model. We aimed the cosine-corrected irradiance probe at where the viewer 271 would be perched during a butterfly model presentation (figure S2). Hence, when taking the 272 relevant irradiance measurements that contributed to butterfly model radiance (via reflection from 273 the model) the probe was held at the position in the horizontal plane where the butterfly model 274 would pass, at a distance of 1 m from the perch, and aimed at the hemisphere which includes the

275 potential perching point of the male (figure S2). The radiance reflected from the background is 276 determined by the light environment from the hemisphere facing the direction of the butterfly 277 model, and the perched male. When taking irradiance measurements that contribute to 278 background radiance (via reflection) the probe was held at the position in the horizontal plane 279 closest to the background type (sand or vegetation), and aimed at the hemisphere which includes 280 the butterfly model (figure S2). Because males can perch either on the hackberry tree or on the 281 ground in front of the tree, both positions were used for taking the irradiance measurements. 282 Because males perched on hackberry exhibit a wide range of orientations, with no significant 283 mean vector in relation to sun azimuth or point of compass in the field (Rutowski at al. 1991), the 284 five perch site locations selected were focused on hackberry trees oriented 90° relative to sun 285 azimuth (99 +/- 44°). To characterize backgrounds of blue sky we took irradiance measurements 286 of blue sky background that was relevant to the orientation of males perched on ground 287 (Rutowski et al. 1991), the probe was held at the position of perched males, and aimed at blue 288 sky, 180 degrees from sun azimuth. As with reflectance spectra, we binned the irradiance data 289 into 1 nm bins from 300 to 700nm using CLR (Montgomerie 2008). Irradiance was then converted to photon flux units relevant for vision (photons/cm<sup>2</sup>/sec). 290

291

292 Visual System Model

We modeled *A. leilia* luminance contrast by calculating achromatic contrast using a von Kries term that assumes receptor adaptation *sensu* Morehouse & Rutowski (2010). Insects have been found to detect motion using luminance contrast from a single spectral photoreceptor type with peak absorption ( $\lambda_{Rmax}$ ) in the green region (Briscoe and Chittka 2001) Therefore, we

297 incorporated a visual pigment with  $\lambda_{Rmax}$  of 530nm found in a related nymphalid species,

*Vanessa cardui* (Briscoe *et al.* 2003) - photoreceptor absorbances are unknown for *A. leilia* - and
a rhodopsin template (Govardovskii 2000) into our model. We then calculated luminance
contrasts between butterfly models and backgrounds according to a log linear model of
photoreceptor quantum catch with a von Kries transformation for receptor light adaptation:

$$q_{\rm G} = \ln\left(\frac{Q_{\rm G}}{Q_{\rm GB}}\right)$$

302 Where  $q_G$  is the quantum catch of a green photoreceptor with peak sensitivity at 530nm.

$$Q_{G} = \int R(\lambda)I(\lambda)A_{G}(\lambda)d\lambda$$
$$Q_{GB} = \int R_{B}(\lambda)I(\lambda)A_{G}(\lambda)d\lambda$$

R( $\lambda$ ) is the averaged reflectance from a target, R<sub>B</sub> is the averaged reflectance from a background type, I( $\lambda$ ) is the relevant ambient irradiance (photons/cm<sup>2</sup>/sec), and A<sub>G</sub>( $\lambda$ ) is the modeled photoreceptor absorbance. We integrated these equations from 300-700nm. All background types are either diffusely reflecting surfaces (sand and vegetation), or diffuse light sources (blue sky), allowing direct comparisons. The calculated luminance contrasts between various butterfly models and backgrounds were compared to the response patterns of males in the field in order to test the prediction that high contrast should result in a high probability of males responding.

#### 311 Results

## 312 *Effect of butterfly model type*

Across presentations, regardless of background and perch locations, model type strongly affected the probability that a male responded by leaving his perch to chase the model (Figure 3a; Table 1). 87% of the males responded when the black model was presented but only 26% responded to presentations of the white model. 52% of the males responded to the gray model and 60%

317 responded to the tan colored model. The response to the black model was significantly higher 318 than the response to the three other model types (Table 2). Likewise, the response to the white 319 model was significantly lower than all other models (Table 2). However, there was no difference 320 in male response to gray and tan colored models (Table 2).

321

## 322 Effect of perch location

323 Male perch location also affected the male's probability of responding to the presented models. 324 As reported in Rutowski et al. (2001) males that were perched on the ground were more likely to 325 respond to the presented models than males perched on a hackberry tree (Figure 3b; Chi-square test:  $X^2 = 7.87$ , P = 0.005). This was true for all four model types, but seemingly stronger in the 326 327 tan colored model (Figure 3b). When the tan colored model was presented for males perching on 328 ground, 86% of the males responded. When the tan colored model was presented for males 329 perching off ground, significantly fewer males, only 44% responded by sallying after the model 330 (Fisher's exact test: P = 0.017).

331

# 332 Effect of background

333 In this study, we have described the background type as one of three discrete categories: sky, 334 sand or vegetation. In 54% of the presentations, the male viewed the passing model against a 335 background that consisted of 90-100% of a single background type. The background never 336 contained less than 50% of a single background type. We find an overall effect of the main 337 background type on the probability that male's would respond to the presented models (Figure 338 3c; Table 1). Males that viewed models against a background of mostly sky were more likely to 339 respond (87%) than males which viewed the model with vegetation (45%), or sand (50%) as the 340 background (Figure 3c). There was no effect of interaction between butterfly model and

background type (Table 1). The strength of the background effect differed slightly betweenmodel types but was strongest for the tan colored model (Figure 3c).

343

344 *Luminance contrast* 

345 The luminance contrast between the presented butterfly model and the background varied with 346 model type. The contrast was highest against all backgrounds for the black model. The contrast 347 was lower for the other three models with small differences between the models (Figure 4a). 348 However, the white model differed from the other three models in the directionality of the 349 contrast. The white model often had a higher luminance than the background while the tan, grey 350 and black models most often were darker than the background. Consequently, the absolute 351 contrast between the white model and the background were similar to the contrast between the 352 grey model and the background, and the tan model and the background, but with an essential 353 difference in the directionality of the contrast. Nevertheless, the contrast values were largely 354 correlated with the behavioral responses for three of the four models (figure 4a). The most 355 contrasting butterfly model (black) generated the highest response from males, while the models 356 with a lower contrast generated a lower behavioral response from males.

357

The luminance contrast also varied with background. Here, the contrasts between models and background are greatest when the background is blue sky than when the background is sand or vegetation (figure 4b). Again the pattern of change in contrast with background parallels the behavioral data where across model types males responded most frequently when blue sky was the background than when sand or vegetation were the background (cf. figure 3c). But again, there is little difference in absolute contrast between the white model and the three background

types (figure 4b), but reversal in contrast directionality. When the white model is viewed against
the vegetation or the sand it had a higher luminance than the background.

366

#### 367 Discussion

368 Our results show that both the brightness of an object as well as the background against which it 369 is viewed strongly affects male probability of detecting the object and initiating a pursuit flight. 370 Perched males are most likely to detect and pursue dark objects such as the black models when 371 they pass by. Moreover, objects were most likely to be detected when viewed against a bright 372 uniform background such as blue sky compared to a background of vegetation or sand. Our 373 modeling of perceived brightness contrast between the presented butterfly models and the 374 background correlates with the behavioral data, at least for three of the four butterfly models. 375 Hence, we argue that the effect of model brightness and background type can be largely 376 explained by differences in achromatic luminance contrast and that a high contrast between 377 object and background facilitates visual detection of small fast moving objects. However, the 378 response to white objects is far lower than would be expected by our measured luminance 379 contrast.

380

## 381 Characterization of background

We acknowledge a few potential sources of error in our measurement techniques. First, we did not determine the background against which a male was viewing the model at the moment he responded. However, not knowing this is mitigated by two features of the backgrounds data. First, in 42% of all presentations from the male's perspective there was only one background type, sky, sand or vegetation, along the model flight path. Second, in cases where there were mixtures of backgrounds there was often one background type that dominated the scene. Also,

388 when there was a mixture of backgrounds, the response from the males was not significantly 389 different than when there was only a single background (table S1). Hence, we contend that using 390 the main background is a good estimation of what the background was at the point the male 391 responded.

392

393 Second, our background categories gloss over complexity within categories. Especially 394 vegetation is likely to be a matrix of bright and dark parts. The result would be that the luminance 395 contrast between a passing object and the background would shift repeatedly and quickly when 396 viewed by the male. It is unknown how this would affect visual detection. However, this effect of 397 this variation is mitigated by the fact that the acuity of male eyes is such that this variation will 398 not be resolved, especially when the background is several meters or more away. The perceived 399 luminance variation will effectively be averaged, resulting in a fairly constant luminance contrast 400 of a passing object. Switzer and Eason (2000) found that in a territorial dragonfly, intruders 401 viewed against distant vegetation were more readily detected than intruders viewed against near 402 vegetation.

403

404 Lastly, our field irradiance measurements used to calculate this contrast may not have captured 405 accurately all of the background light which was present. Specifically our measurements omitted 406 the skylight, a major extrinsic factor in desert ecosystems, which would contribute to background luminance. Further, the light contributing to background luminance comes from a larger field of 407 408 view than is represented by measuring vector irradiance, which by necessity is restricted to the 409 hemisphere in which a cosine-corrected collector is directed. Nevertheless, the effect of scattered 410 background light is predicted to increase perceived luminance contrast of objects which have less 411 luminance than the background (black, tan and gray models), but also to decrease the perceived

412 contrast of objects which have a higher luminance than the background (white model). This
413 would explain why the measured luminance contrast of the white target is higher than predicted
414 by behavioral responses, and the contrast for the three other models is slightly lower than
415 predicted by the behavioral responses, as seen in Figure 4a. Further, we find that the deviation is
416 larger when the background was sand, or vegetation (Figure 4b), which could be explained due to
417 a stronger effect of scattered skylight. As overall levels of direct illumination decrease, the
418 proportion of scattered skylight contributing to ambient illumination is higher.

419

# 420 Visual modeling and luminance contrast

421 By using physiological models of color processing we explored the role that perceived luminance 422 contrast between object and background might play in explaining these results. The models we 423 used are built on several assumptions. First, the model assumes that the spectral sensitivity of A. 424 leilia is similar to that of Vanessa cardui. Second, the model assume that A. leilia use mainly 425 their green receptor for target detection. It is well known that bees use their green receptor for 426 target detection (Giurfa & Vorobyev 1997, 1998) but it is still largely unknown how this works in 427 butterflies. However, which visual pathway (chromatic or achromatic) is used for target detection 428 in bees depends on the angle subtended by the target. If a target subtends an angle above  $30^\circ$ , 429 color vision is used for target detection and recognition. But if a target is small and close to detection limits (subtends less than 5° in the visual field) detection is guided by the long 430 431 wavelength photoreceptor class alone (Giurfa & Vorobyev 1997, 1998). The long wavelength 432 photoreceptor is used to see the intensity differences between the object and the background, a 433 mechanism also referred to as "green contrast" (Giurfa et al. 1996). Behavioral studies also 434 suggest that butterflies use achromatic vision and target-background intensity contrast for some 435 behavioral tasks, such as landing on flowers (Koshitaka et al. 2011). In our study we did not find

436 any difference in the males' response to the gray model and the tan colored model (Table 2; 437 Figure 3a). The gray and the tan colored models are similar in brightness but differ in spectral 438 properties (Figure 1). The similarity in response to the gray and tan model may indicate that A. 439 *leilia* also uses an achromatic rather than a chromatic visual pathway to detect small passing 440 objects. Based on this and considering that the butterfly models at the distance presented in our 441 study subtended less than 5° in the perched male's visual field, we conclude that males use only 442 their long wave receptor for detection of the presented models. Hence, given that the assumptions 443 made by our visual model are correct, we can infer that perched males of A. leilia use mainly 444 luminance and not color contrast to detect flying females and other males.

445

## 446 Contrast directionality and response to white objects

447 The comparison of the behavioral data and the measured luminance contrast between the 448 butterfly models and the background show that the white model deviates from the correlation 449 between behavior and measured luminance contrast. As mentioned above, it is likely that our 450 natural irradiance measurements were unable to accurately capture all of the background light 451 which was present and that we thereby underestimate the background luminance perceived by the 452 perched males. However, there is also a small possibility that there is an additional, biological 453 explanation for this mismatch. Two other studies, where artificial butterfly-shaped models have 454 been presented to perched butterfly males in the field, reported a very low response to white objects (Stride 1957; Tinbergen et al. 1972). The species studied were both nymphalids 455 456 (*Hipparchia semele* and *Hypolimnas misippus*) and Stride (1957) proposed an adaptive 457 explanation to the low response to white objects. Since perching behavior involves costly 458 approach flights and investigation of essentially anything that comes into the visual field, a 459 mechanism that allows discrimination would be an advantage for the male. Approach inhibition

based on brightness of the object would avoid pursuit of butterflies in the family Pieridae, a family with many species of white butterflies (Stride 1957). Even though an underestimation of background luminance seems likely to explain the low response to white models in *A. leilia*, if is not impossible that there is a general approach inhibition towards white objects in perching species and that this could be the result of undescribed visual system response that detect the direction of contrast rather than only the magnitude and affects a male's decision to take off and pursue a passing object.

467

468 Conclusions

469 Studies like the one presented here, that examine how extrinsic factors such as background affect 470 visual detection under natural settings complement previous studies on intrinsic factors, i.e. how 471 visual systems work and how morphological and physiological features affect visual 472 performance. By taking the experiment to the field we can test hypotheses about how natural 473 variation and real environmental factors affect visual system performance. Studies like this are 474 also important to understand the behavioral and evolutionary ecology of a perch-and-sally 475 strategy. Males of A. leilia can affect their success at detecting and pursuing passing females by 476 choosing a perch site that facilitate this task. By studying this in wild males found on their natural 477 perch sites we can understand the variation in real environmental factors and how this will 478 structure selection for choosing preferred perch sites. In an earlier study, Bergman and Wiklund 479 (2009) studied visual mate detection in the speckled wood butterfly (*Pararge aegeria*), a species 480 in which males defend mating territories in large sunspots on the forest floor (Davies 1978; 481 Wickman & Wiklund 1983). Bergman and Wiklund (2009) showed that males enhance their 482 chance of visually detecting passing females by preferring to perch in large sunspots over small 483 ones. In this system the background varies little between perch sites, but the level of ambient

484 illumination in the sunspot facilitates visual detection of passing females, presumably because a 485 female entering the sunspot will be illuminated by the sun, appear brighter and thereby contrast 486 more with the dark forest background. Further, a female passing a male sitting in a large sunspot 487 will be illuminated by the sun for a longer time than a female passing a male in a small sunspot, 488 and thereby more likely to be detected. Similar to A. leilia, males of P. aegeria can increase the 489 chance of viewing a passing female at a high contrast to the background by the choice of perch 490 site. We argue that this and other extrinsic factors have large effects on the success of perch-and-491 sally tactics and ultimately on the evolution of perch site preferences.

492

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498

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596 Figure legends

597 Figure 1

598 Reflectance spectra of the four butterfly models presented to perched males of *Asterocampa*599 *leilia*.

600 Figure 2

601 Background classification images taken after presentations of butterfly models to males of

602 *Asterocampa leilia*. Each photo was taken from the exact spot the male was perched. The black

603 line shows the flight path of the model. (a) represents a background consisting of mainly sky, (b)

604 represents a background consisting of mainly sand and (c) represents a background consisting of

605 mainly vegetation.

606 *Figure 3* 

607 The relationship between the proportion of perched males responding as a function of model

608 type: (A) for all presentations, (B) for all males as a function of perch location, and (C) for all

males as a function of main background type. For all graphs, the number adjacent to each data

610 point is the number of presentations with that model type.

611 Figure 4

612 (A) The relationship between the proportion of perched males responding as a function of model

613 type for all presentations (right y-axis), and luminance contrast as a function of model type (left

614 y-axis). (B) Luminance contrast as a function of model type and background.

615

## 616 Figure legends supplementary figures

617 Figure S1.

618 Reflectance spectra of the tan butterfly model, presented to perched males of Asterocampa leilia,

and the ventral hindwing of *A.leilia* females. The gray areas show the 95% CI. The average

620 reflectance of the tan model is not significantly different from female ventral hindwing average 621 reflectance (t-test:  $t_4 = 1.88$ , P > 0.05).

622 Figure S2.

623 Diagram of irradiance and radiance of viewer, butterfly model and background. Black butterfly 624 represents a perched A. leilia male and grey butterfly represents presented butterfly model. Red 625 arrows represent radiance and blue arrows represent irradiance. Thick arrows represent the model 626 while dashed is for background. B represents background. (a) illustrates a male perched in the 627 hackberry tree viewing the model with a sand background. (b) illustrates a male perched on a 628 hackberry tree viewing the model against a vegetation background. (c) illustrates a male perched 629 on the ground viewing the model against the blue sky. (d) illustrates a male perched on the 630 ground viewing the model against a vegetation background. 631

632 Tables

633 *Table 1* 

634 The results from a Generalized Equation Estimates (GEE) showing the effect of model type and
635 background on the probability of getting a response from a perched male to a presented butterfly
636 model.

Factor	d.f.	Wald $\chi^2$	Р
Model type	3	28.53	< 0.001
Background type	2	7.51	0.023
Model type x Background type	6	5.83	0.44

637

638 *Table 2* 

639 The result of six pairwise McNemara's tests between four butterfly model types. After correction

640 of the alpha-values with a sequential Bonferroni all pairwise tests are significant, except the

641 difference between the gray and the tan model, which is not significant.

		Model type			
		Black	Gray	Tan	White
Model type	Black		χ <sup>2</sup> =12.07	χ <sup>2</sup> =10.08	χ <sup>2</sup> =21.04
			<i>P</i> <0.001	P=0.0015	<i>P</i> <0.001
	Gray			$\chi^{2}$ =0.57	$\chi^2 = 6.72$
				P=0.45	P=0.0095
	Tan				χ <sup>2</sup> =10.32
	Tan				P=0.0013
	White				

642

# 644 Supplementary table

645 Table S1

646 The response to presented butterfly models by perched males of *A. leilia*. The proportion of males

647 that responded and that viewed the model against a single background type was not significantly

648 different from the proportion of males that responded which viewed the model against a mixture

649 of background types.

Model	Responded	Single	Mixture	
type		background	of backgrounds	
Plack	Yes	17	21	$x^2 - 1.00: n - 0.32$
DIACK	No	4	2	$\chi$ =1.00, <i>p</i> =0.32
Grav	Yes	9	15	$x^2 = 0.06$ ; n=0.81
Glay	No	9	13	$\chi$ =0.00, <i>p</i> =0.81
Tan	Yes	9	18	$x^2 - 3$ 38: $n = 0.07$
Tall	No	11	7	χ =3.38, p=0.07
\\/bito	Yes	6	5	$x^2 - 1.00$ ; n=0.17
white	No	10	22	$\chi = 1.90, p = 0.17$

650

# 652 Figures

653 Figure 1



654





Model type



665 Figure S1



666

667 Figure S2

